emulating `termux-location`

to bodge surplus on wheels (s+ow) on non-Termux systems

> ℹ️ **Note**
>
> dummy admonition for colour matching

> ⚠️ **Warning**
>
> dummy admonition for colour matching

`termux-location`, part of Termux:API, gets the device's location via android apis and returns a json response through stdout:

```
{
    "latitude": 1.3277513,
    "longitude": 103.678317,
    "altitude": 51.6298828125,
    "accuracy": 48.46337890625,
    "vertical_accuracy": 38.4659423828125,
    "bearing": 0.0,
    "speed": 0.0,
    "elapsedMs": 28,
    "provider": "gps"
}
```

see https://wiki.termux.com/wiki/Termux-location for more information

implementing for surplus on wheels (s+ow)

s+ow will call the command a total of six times, being three pairs of parallel `$LOCATION_CMD -p "network"` and `$LOCATION_CMD -p "gps"` invocations, before deciding after exhausting all six runs on which output to choose, if any command runs were successful

even if somewhere in the termux-location implementation fails, it always (begrudgingly) returns zero. s+ow will treat the invocation of the command as successful if there is **any output** to the standard output (stdout) stream

implementing for surplus (s+)

s+, when passed `--t` / `--using-termux-location`, will consume stdin, parse it as json and then attempt to retrieve the `latitude` and `longitude` keys as floating point numbers